

# Variational inference via Wasserstein gradient flows

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# Outline

- 1 Problem
- 2 Variational inference
- 3 Gradient flows in  $BW(\mathbb{R}^d)$
- 4 Theoretical guarantees
- 5 Mixtures of Gaussians

# Problem

## Variational inference

Given a target distribution  $\pi \propto \exp(-V)$ , determine an approximation:

$$\hat{\pi} \in \arg \min_{p \in \mathcal{P}} \text{KL}(p\|\pi),$$

where  $\mathcal{P}$  is an ambiguity set.

The Kullback–Leibler (KL) divergence is defined as:

$$\text{KL}(p\|\pi) = \begin{cases} \int_{\mathcal{X}} \log \left( \frac{dp}{d\pi}(x) \right) d\pi(x), & \text{if } p \ll \pi, \\ \int_{\mathcal{X}} p(x) \log \left( \frac{p(x)}{\pi(x)} \right) dx, & \text{if } p, \pi \ll \text{Leb.} \end{cases}$$

# Bayesian inference

## Bayesian inference framework

We want to make inference (e.g., compute expectation, covariance...) on a posterior distribution  $\pi$  on a space  $\Theta$ :

$$\pi(\theta) := p(\theta | x) = \frac{p(x | \theta)p(\theta)}{p(x)}.$$

Defining the *potential*  $V(\theta) = -\log(p(x | \theta)) - \log(p(\theta))$ , then  $\pi \propto \exp(-V)$ .

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Two approaches:

- Monte Carlo Markov chains (**MCMC**);
- Variational inference (**VI**).

# MCMC

**Idea:** build a Markov chain  $(X_t)_{t \geq 0}$  with  $\pi$  as stationary distribution. Then take  $(X_t)_{t \geq \bar{t}}$  as samples from  $\pi$ .

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## Langevin MC

$(X_t)_{t \geq 0}$  are solution of the *Langevin SDE*

$$dX_t = -\nabla V(X_t)dt + \sqrt{2}dB_t \quad (1)$$

where  $(B_t)_{t \geq 0}$  is the standard Brownian motion.

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The marginal laws  $\mu_t$  of the solution of  $(X_t)_{t \geq 0}$ , are the solution of the *Fokker-Planck PDE*

$$\partial_t \mu_t = \text{div}(\mu_t \nabla \log \frac{\mu_t}{\pi})$$

and it converges to the stationary distribution  $\pi$

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## Langevin MC

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$$dX_t = -\nabla V(X_t)dt + \sqrt{2}dB_t \quad (2)$$

where  $(B_t)_{t \geq 0}$  is the standard brownian motion.

## Advantages:

- samples from real distribution;
- non-asymptotic guarantees when  $\pi$  is strongly log-concave.

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- samples from real distribution;
- non-asymptotic guarantees when  $\pi$  is strongly log-concave.

### Disadvantages:

- generally slow, in particular in high-dimensional settings.

## VI

## Variational inference

The *VI* setting consists in finding a tractable approximation  $\hat{\pi}$  of  $\pi$  solving

$$\hat{\pi} \in \operatorname{argmin}_{p \in \mathcal{P}} \text{KL}(p || \pi)$$

and then computing the quantity of interests on  $\hat{\pi}$ .

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- theoretical guarantees?

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In the paper, the problem is addressed in the cases of

- $\mathcal{P} = BW(\mathbb{R}^d) := \{\text{non-degenerate } d\text{-dimensional Gaussians}\};$
- $\mathcal{P} = \{\text{mixtures of } d\text{-dimensional Gaussians}\}.$

# Particle system

## Theorem

Given  $(X_t)_{t \geq 0}$  solutions of the Langevin diffusion, with  $X_t \sim \pi_t$ ,  $m_t = \mathbb{E}[X_t]$  and  $\Sigma_t = \text{cov}(X_t)$ , then

$$\dot{m}_t = -\mathbb{E}_{\pi_t}[\nabla V(X_t)]$$

$$\dot{\Sigma}_t = 2I - \mathbb{E}_{\pi_t}[\nabla V(X_t) \otimes (X_t - m_t) + (X_t - m_t) \otimes \nabla V(X_t)]$$

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## Särkkä's heuristic

Taking  $Y_t \sim p_t = \mathcal{N}(m_t, \Sigma_t)$ , the system of ODE

$$\dot{m}_t = -\mathbb{E}_{p_t}[\nabla V(Y_t)]$$

$$\dot{\Sigma}_t = 2I - \mathbb{E}_{p_t}[\nabla V(Y_t) \otimes (Y_t - m_t) + (Y_t - m_t) \otimes \nabla V(Y_t)]$$

yields to an evolution  $(p_t)_{t \geq 0}$  of gaussians.

# Problem geometry

## Optimization problem

$$\hat{\pi} \in \operatorname{argmin}_{p \in \mathcal{P}} \text{KL}(p || \pi)$$

where  $\mathcal{P} = \{p_\theta : \theta \in \Theta\}$

The choice of  $\mathcal{P}$  determines the geometry of the searching problem.

- In  $\mathbb{R}^d$ :  $\dot{x}_t = -\nabla F(x_t)$   
(*"continuous-time" gradient descent*)
- In  $\mathcal{P} = BW(\mathbb{R}^d)$ :  $\partial_t \mu_t = -\nabla_{BW} \mathcal{F}(\mu_t)$   
(*gradient flow*)

$\nabla_{BW}$ ? Discretization?

# Results

**Claim:** The gradient flow of  $KL(\cdot||\pi)$  in the space  $BW(\mathbb{R}^d)$  endowed with the Wasserstein distance solves Särkkä's ODEs.

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An extension with  $\mathcal{P}$  as space of mixtures of Gaussian is then derived.

# Wasserstein space

## Riemannian structure

We consider  $\mathcal{P}_2(\mathbb{R}^d)$  with the following Riemannian structure (Otto):

$$T_\mu \mathcal{P}_2(\mathbb{R}^d) = \{\nabla \psi \mid \psi : \mathbb{R}^d \rightarrow \mathbb{R}\}, \quad \mu \in \mathcal{P}_2(\mathbb{R}^d)$$

$$\langle v, w \rangle_\mu = \int_{\mathbb{R}^d} \langle v(\theta), w(\theta) \rangle_{\mathbb{R}^d} d\mu(\theta), \quad v, w \in T_\mu \mathcal{P}_2(\mathbb{R}^d)$$

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## Metric structure

$\mathcal{P}_2(\mathbb{R}^d)$  is a metric space with the *Wasserstein metric* (Benamou - Brenier):

$$W_2^2(\mu_0, \mu_1) = \inf \left\{ \int_0^1 \| \nabla \xi \|_{\mu_t}^2 dt \mid \partial_t \mu_t = -\operatorname{div}(\mu_t \nabla \xi) \right\}$$

# Bures-Wasserstein space

$BW(\mathbb{R}^d)$  is identified with  $\mathbb{R}^d \times \mathbf{S}_{++}^d$ , where  
 $\mathbf{S}_{++}^d = \{\Sigma \in \mathbb{R}^{d \times d} \mid \Sigma \succ 0, \Sigma^t = \Sigma\}$ .

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## Riemannian structure

In particular, the tangent space is identified with

$$T_p BW(\mathbb{R}^d) = \{x \mapsto a + S(x - m_p) \mid a \in \mathbb{R}^d, S \in \mathbf{S}^d\} \cong \mathbb{R}^d \times \mathbf{S}^d$$

where  $\mathbf{S}^d = \{S \in \mathbb{R}^{d \times d} \mid S^t = S\}$ .

# Gradient flows in $BW(\mathbb{R}^d)$

**Goal:** derive gradient flows  $(p_t)_{t \geq 0}$  of  $\text{KL}(\cdot \mid \pi)$  in  $BW(\mathbb{R}^d)$ .

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- *Bures-JKO scheme* (proximal point algorithm):

## Bures-JKO scheme

Given  $h > 0$ ,

$$p_{k+1,h} := \underset{p \in BW(\mathbb{R}^d)}{\operatorname{argmin}} \left\{ \text{KL}(p \parallel \pi) + \frac{1}{2h} W_2^2(p, p_{k,h}) \right\}$$

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We then define  $p_t := \lim_{h \rightarrow 0} p_{\lfloor t/h \rfloor, h}$

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- *Direct computation of Bures-Wasserstein gradient.*

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## Bures-Wasserstein gradient

$$\nabla_{BW} f(m, \Sigma) = (\nabla_m f(m, \Sigma), 2\nabla_\Sigma f(m, \Sigma))$$

$$\nabla_{BW} \text{KL}(p \parallel \pi) = (\mathbb{E}_p[\nabla V], \mathbb{E}_p[\nabla^2 V] - \Sigma_p^{-1})$$

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## Gradient flow

In the previous ways, we obtain  $\nabla_{BW} KL(\mu \parallel \pi)$  in  $\mu$ . The gradient flow  $(p_t)_{t \geq 0}$  in  $BW(\mathbb{R}^d)$  is a solution of

$$\partial_t p_t = -\nabla_{BW} KL(p_t \parallel \pi)$$

# Särkkä equivalence

## Theorem

$(p_t = p_{(m_t, \Sigma_t)})_{t \geq 0}$ , gradient flow of  $\text{KL}(\mu \parallel \pi)$  in  $BW(\mathbb{R}^d)$ ,  
satisfies Särkkä's system of ODEs

$$\dot{m}_t = -\mathbb{E}[\nabla V(Y_t)]$$

$$\dot{\Sigma}_t = 2I - \mathbb{E}[\nabla V(Y_t) \otimes (Y_t - m_t) + (Y_t - m_t) \otimes \nabla V(Y_t)]$$

# Continuous-time convergence

## $\alpha$ -convexity

We say  $\mathcal{F}$ , functional on  $BW(\mathbb{R}^d)$ , is  $\alpha$ -convex for  $\alpha \in \mathbb{R}$  if, on the constant-speed geodesic  $(p_t)_{t \in [0,1]}$ ,

$$\mathcal{F}(p_t) \leq (1-t)\mathcal{F}(p_0) + t\mathcal{F}(p_1) - \alpha \frac{t(1-t)}{2} \mathcal{W}_2^2(p_0, p_1)$$

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## Lemma

For any  $\alpha \in \mathbb{R}$ ,  $\nabla^2 V \succeq \alpha I$  ( $\pi$  strongly log-concave), then  $\text{KL}(\cdot \parallel \pi)$  is  $\alpha$ -convex on  $BW(\mathbb{R}^d)$ .

# Continuous-time convergence

## Corollary

Let  $\nabla^2 V \succeq \alpha I$  for a certain  $\alpha \in \mathbb{R}$ . Then, for any  $p_0 \in BW(\mathbb{R}^d)$ , there exists a unique solution for the gradient flow in  $BW(\mathbb{R}^d)$  of  $KL(\cdot || \pi)$  started at  $p_0$ . Moreover,

- ① If  $\alpha > 0$ , then for all  $t \geq 0$ ,

$$W_2^2(p_t, \hat{\pi}) \leq \exp(-2\alpha t) W_2^2(p_0, \hat{\pi})$$

- ② If  $\alpha > 0$ , then for all  $t \geq 0$ ,

$$KL(p_t \parallel \pi) - KL(\hat{\pi} \parallel \pi) \leq \exp(-2\alpha t) \{KL(p_0 \parallel \pi) - KL(\hat{\pi} \parallel \pi)\}$$

- ③ If  $\alpha = 0$ , then for all  $t > 0$ ,

$$KL(p_t \parallel \pi) - KL(\hat{\pi} \parallel \pi) \leq \frac{1}{2t} W_2^2(p_0, \hat{\pi})$$

# Discretization

To discretize in  $t$  the gradient flow  $(p_t)_{t \geq 0}$ , two approaches are possible:

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To discretize in  $t$  the gradient flow  $(p_t)_{t \geq 0}$ , two approaches are possible:

- Numerical integration of Särkkä's system of ODE

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with  $Y_t \sim p_t = \mathcal{N}(m_t, \Sigma_t)$

**Drawback:** theoretical guarantees?

# Discretization

- Bures-Wasserstein SGD algorithm.

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## Algorithm Bures-Wasserstein SGD

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**Require:**  $\alpha > 0$ , step size  $h > 0$ ,  $m_0$  and  $\Sigma_0$

```
1: for  $k = 1, \dots, N$  do
2:   Draw a sample  $\hat{X}_k \sim p_k$ 
3:    $m_{k+1} \leftarrow m_k - h \nabla V(\hat{X}_k)$ 
4:    $M_k \leftarrow I - h(\nabla^2 V(\hat{X}_k) - \Sigma_k^{-1})$ 
5:    $\Sigma_k^+ \leftarrow M_k \Sigma_k M_k$ 
6:    $\Sigma_{k+1} \leftarrow \text{clip}_{1/\alpha} \Sigma_k^+$ 
7: end for
```

---

It can be shown that

$$p_k^+ := p_{m_{k+1}, \Sigma_k^+} = \exp_{p_k}(-h \nabla_{\text{BW}} \text{KL}(p_k \parallel \pi)(\hat{X}_k)) \quad (\text{SG step of } h).$$

# Non-asymptotic results

## Theorem

Assume that  $0 \prec \alpha I \preceq \nabla^2 V \preceq I$  ( $\pi$  strongly log-concave and log-smooth). Also, assume that  $h \leq \alpha^2/60$  and that we initialize Algorithm 1 at a matrix satisfying  $\frac{\alpha}{9}I \preceq \Sigma_{\mu_0} \preceq \frac{1}{\alpha}I$ . Then, for all  $k \in \mathbb{N}$ ,

$$\mathbb{E}[W_2^2(p_k, \hat{\pi})] \leq \exp(-\alpha kh) W_2^2(p_0, \hat{\pi}) + \frac{36dh}{\alpha^2}.$$

In particular, we obtain

$$\mathbb{E}[W_2^2(p_k, \hat{\pi})] \leq \varepsilon^2$$

provided we set  $h \asymp \frac{\alpha^2 \varepsilon^2}{d}$  and the number of iterations to be  $k \gtrsim \frac{d}{\alpha^3 \varepsilon^2} \log \left( \frac{W_2(p_0, \hat{\pi})}{\varepsilon} \right)$ .

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## Drawbacks:

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The drawback can be addressed by extending the previous model to mixtures of Gaussians.

## Theorem

The set of the  $d$ -dimensional Gaussian mixtures is dense in  $\mathcal{P}_2(\mathbb{R}^d)$  for the metric  $W_2$ .

# Geometry of the problem

The space of mixtures of Gaussians can be identified with  $\mathcal{P}_2(BW(\mathbb{R}^d))$  through this relation

$$\mu \in \mathcal{P}_2(\Theta) \quad \longleftrightarrow \quad p_\mu := \int_{\Theta} p_\theta d\mu(\theta)$$

where  $\Theta = \mathbb{R}^d \times \mathbf{S}_{++}^d \cong BW(\mathbb{R}^d)$ .

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where  $\Theta = \mathbb{R}^d \times \mathbf{S}_{++}^d \cong BW(\mathbb{R}^d)$ .

## Remark

The theory of optimal transport can be derived again in the space  $\mathcal{P}_2(\mathcal{M})$  where  $\mathcal{M}$  is a Riemannian manifold, in particular it is well-defined the gradient flow of  $\mu \mapsto \text{KL}(p_\mu \parallel \pi)$  in  $\mathcal{P}_2(BW(\mathbb{R}^d))$ .

# Interacting particles algorithm

Let  $\mu \in \mathcal{P}(BW(\mathbb{R}^d)) \mapsto \mathcal{F}(\mu) = KL(p_\mu \parallel \pi) \in \mathbb{R} \cup \{\infty\}$ .

## Theorem

The gradient flow  $(\mu_t)_{t \geq 0}$  of the functional  $\mathcal{F}$  over  $\mathcal{P}_2(BW(\mathbb{R}^d))$  can be described as follows. Let  $\theta_0 = (m_0, \Sigma_0) \sim \mu_0$ , and let  $\theta_t = (m_t, \Sigma_t)$  evolve according to the system of ODEs:

$$\dot{m}_t = -\mathbb{E}[\nabla \log \frac{p_{\mu_t}}{\pi}(Y_t)],$$

$$\dot{\Sigma}_t = -\mathbb{E}\left[\nabla^2 \log \frac{p_{\mu_t}}{\pi}(Y_t)\right] \Sigma_t - \Sigma_t \mathbb{E}\left[\nabla^2 \log \frac{p_{\mu_t}}{\pi}(Y_t)\right],$$

where  $Y_t \sim \mathcal{N}(m_t, \Sigma_t)$ . Then  $\theta_t \sim \mu_t$ .

# Interacting particles algorithm

To implement the *Gaussian particles* scheme we take  $N < \infty$  Gaussian particles, i.e., mixtures of  $N$  Gaussians

$$\mu_0 = \frac{1}{N} \sum_{i=1}^N \delta_{\theta_0^{(i)}} = \frac{1}{N} \sum_{i=1}^N \delta_{(m_0^{(i)}, \Sigma_0^{(i)})} \leftrightarrow p_{\mu_0} = \frac{1}{N} \sum_{i=1}^N p_{(m_0^{(i)}, \Sigma_0^{(i)})}.$$

It follows

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$$\mu_0 = \frac{1}{N} \sum_{i=1}^N \delta_{\theta_0^{(i)}} = \frac{1}{N} \sum_{i=1}^N \delta_{(m_0^{(i)}, \Sigma_0^{(i)})} \leftrightarrow p_{\mu_0} = \frac{1}{N} \sum_{i=1}^N p_{(m_0^{(i)}, \Sigma_0^{(i)})}.$$

It follows

$$\mu_t = \frac{1}{N} \sum_{i=1}^N \delta_{\theta_t^{(i)}} = \frac{1}{N} \sum_{i=1}^N \delta_{(m_t^{(i)}, \Sigma_t^{(i)})} \leftrightarrow p_{\mu_t} = \frac{1}{N} \sum_{i=1}^N p_{(m_t^{(i)}, \Sigma_t^{(i)})}.$$

Or we can use a proximal point method analogous to the

Bures-JKO scheme:

$$(\theta_t^{(1)} + h, \dots, \theta_t^{(N)} + h) \approx$$

$$\approx \underset{\theta^{(1)}, \dots, \theta^{(N)} \in \Theta}{\operatorname{argmin}} \left[ \text{KL} \left( \frac{1}{N} \sum_{i=1}^N p_{\theta^{(i)}} \middle\| \pi \right) + \frac{1}{2Nh} \sum_{i=1}^N W_2^2(p_{\theta^{(i)}}, p_{\theta_t^{(i)}}) \right].$$

# Pros and cons

## Advantages:

- (Hope of) asymptotic convergence to an arbitrary good approximation of the target distribution  $\pi$  given  $N$  sufficiently large.

## Drawbacks:

- Lack of theoretical guarantees as in Gaussian VI and Langevin MC because

$$\mu \mapsto \text{KL}(p_\mu \parallel \pi)$$

is in general not convex, even if  $\pi$  is strongly log-concave.

# Extensions with changing weights

In the paper a possible extension is suggested to take into account mixtures of Gaussians with changing weights:

$$\mu_t = \sum_{i=1}^N w_t^{(i)} \delta_{(m_t^{(i)}, \Sigma_t^{(i)})} \leftrightarrow p_{\mu_t} = \sum_{i=1}^N w_t^{(i)} p_{(m_t^{(i)}, \Sigma_t^{(i)})}.$$

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**Idea:** use the *Wasserstein-Fisher-Rao (Hellinger-Kantorovich) geometry*, which admits change of mass. Each Gaussian particle is provided with a mass which evolves with the other parameters.

# Extensions with changing weights

## Theorem

Let  $Y_t^{(i)} \sim \mathcal{N}(m_t^{(i)}, \Sigma_t^{(i)})$ , and let  $r_t^{(i)} = \sqrt{w_t^{(i)}}$ . Then, the system of ODEs is given by:

$$\dot{m}_t^{(i)} = -\mathbb{E} \left[ \nabla \log \frac{p_{\mu_t}}{\pi} \left( Y_t^{(i)} \right) \right],$$

$$\dot{\Sigma}_t^{(i)} = -\mathbb{E} \left[ \nabla^2 \log \frac{p_{\mu_t}}{\pi} \left( Y_t^{(i)} \right) \right] \Sigma_t^{(i)} - \Sigma_t^{(i)} \mathbb{E} \left[ \nabla^2 \log \frac{p_{\mu_t}}{\pi} \left( Y_t^{(i)} \right) \right],$$

$$\dot{r}_t^{(i)} = - \left( \mathbb{E} \left[ \log \frac{p_{\mu_t}}{\pi} \left( Y_t^{(i)} \right) \right] - \frac{1}{N} \sum_{j=1}^N \mathbb{E} \left[ \log \frac{p_{\mu_t}}{\pi} \left( Y_t^{(j)} \right) \right] \right) r_t^{(i)}.$$

# Summary

## Results of the paper:

- Gaussian VI framework which close the gap with Langevin MC in terms of theoretical guarantees;
- mixtures of Gaussians VI framework with good empirical results.

## Limits:

- Lack of theoretical guarantees for the mixture of Gaussians model;
- no in-depth analysis of the mixture of Gaussians VI with changing weights and the Wasserstein-Fisher-Rao geometry.

Problem  
o

Variational inference  
oooooooo

Gradient flows in  $BW(\mathbb{R}^d)$   
ooooo

Theoretical guarantees  
ooooo

Mixtures of Gaussians  
oooooooo●

Thank you for your attention!

# Proof of Särkkä's theorem

It is known (Ambrosio et al., 2008):

$$\nabla_{W_2} \text{KL}(\mu \parallel \pi) = \nabla \log \frac{\mu}{\pi}$$

Let  $(\pi_t)_{t \geq 0}$  evolve along the Fokker-Planck PDE.

According to Otto calculus, if  $x_0 \sim \pi_0$  and

$$\dot{x}_t = v_t(x_t) = -\nabla \log \frac{\pi_t}{\pi}(x_t)$$

then  $x_t \sim \pi_t$ .

From explicit computation (integrating by parts) of

$$\dot{m}_t = \partial_t \mathbb{E}_{\pi_t}[x_t]$$

$$\dot{\Sigma}_t = \partial_t \mathbb{E}_{\pi_t}[x_t \otimes x_t] - \partial_t(\mathbb{E}_{\pi_t}[x_t] \otimes \mathbb{E}_{\pi_t}[x_t])$$

follows Särkkä's system of ODEs.

# Bures-JKO scheme

## Gaussian VI

$$\begin{aligned}
 p_{t+h} = \min_{p \in \text{BW}(\mathbb{R}^d)} \mathcal{L}(m, \Sigma) = & \text{KL}(p_{m, \Sigma} \parallel \pi) + \\
 & + \frac{1}{2h} \|m_t - m\|^2 + \frac{1}{2h} \mathcal{B}^2(\Sigma_t, \Sigma)
 \end{aligned}$$

Särkkä's system of ODEs can be derived by computing the critical points from

$$\nabla_m \mathcal{L}(m, \Sigma) = 0$$

$$\nabla_\Sigma \mathcal{L}(m, \Sigma) = 0$$

and then computing the limit for  $h \downarrow 0$ .

The process is analogous to the proximal point algorithm for mixture of Gaussians.

# Otto calculus

In  $\mathcal{P}(\mathbb{R}^d)$ , with Otto-Wasserstein riemannian structure, for every *nice and regular* curve  $(\mu_t)_{t \geq 0}$ , there exist a tangent field  $(v_t = \nabla \phi_t)_{t \geq 0}$  such that

$$\partial_t \mu_t + \operatorname{div}(\mu_t v_t) = 0$$

$$\begin{aligned} W_2^2(\mu_0, \mu_1) &= \inf_{\gamma \in \mathcal{C}(\mu, \nu)} \left\{ \int_{\mathbb{R}^d \times \mathbb{R}^d} \|x - y\|^2 d\gamma(x, y) \right\} \\ &= \int_{\mathbb{R}^d} \|x - T(x)\|^2 d\mu_0 \end{aligned}$$

$$\log_\mu \nu = \nabla \phi_{\mu \rightarrow \nu} - id$$

$$\exp_\mu \nu = (id + v)_\mu$$

# Complements on Bures-Wasserstein space

If  $(p_t)_{t \geq 0}$  is a curve in  $BW(\mathbb{R}^d)$  with tangent vector in time 0 of  $(a, S)$ , then

$$\dot{m}_t = a$$

$$\dot{\Sigma}_t = S\Sigma_0 + \Sigma_0 S$$

For any curve  $(m_t, \Sigma_t)_{t \geq 0}$  with tangent vector  $(a, S)$  at time  $t = 0$  is defined as  $\nabla_{BW} f(m_0, \Sigma_0) = (\bar{a}, \bar{S})$  such that

$$\langle \nabla_{BW} f(m_0, \Sigma_0), (a, S) \rangle_{p_{m_0, \Sigma_0}} = \partial_t|_{t=0} f(m_t, \Sigma_t).$$

$$\langle \bar{a}, a \rangle + \langle \bar{S}, \Sigma_0 S \rangle = \langle \nabla_m f(m_0, \Sigma_0), a \rangle + 2 \langle \nabla_\Sigma f(m_0, \Sigma_0), \Sigma_0 S \rangle.$$

It follows:

$$\nabla_{BW} f(m, \Sigma) = (\nabla_m f(m, \Sigma), 2\nabla_\Sigma f(m, \Sigma)).$$

# Proof of continuous-time convergence

$\mathcal{F}$  functional,  $(p_t)_{t \geq 0}$  and  $(q_t)_{t \geq 0}$  solutions of g.f. of  $\mathcal{F}$ .

$$F(p_t) \geq \mathcal{F}(q_t) + \langle \nabla(\mathcal{F}(q_t)), \log_{q_t}(p_t) \rangle_{q_t} + \frac{\alpha}{2} d^2(p_t, q_t)$$

$$\partial_t d^2(p_t, q_t) \leq -2\alpha d^2(p_t, q_t)$$

$$\text{Grownwall's inequality: } d^2(p_t, q_t) \leq \exp(-2\alpha t) d^2(p_0, q_0)$$

Taking  $q_t = p^*$ ,  $\forall t \geq 0$ , if  $\alpha > 0$

$$\begin{aligned} 0 = \mathcal{F}(p_*) &\stackrel{\text{Conv.}}{\geq} \mathcal{F}(p) + \langle \nabla \mathcal{F}(p), \log_p(p_*) \rangle_p + \frac{\alpha}{2} d^2(p, p_*) \\ &\stackrel{\text{Young}}{\geq} \mathcal{F}(p) - \frac{1}{2\alpha} \|\nabla \mathcal{F}(p)\|_p^2 - \frac{\alpha}{2} \underbrace{\|\log_p(p_*)\|_p^2}_{=d^2(p, p_*)} + \frac{\alpha}{2} d^2(p, p_*) \end{aligned}$$

# Proof of continuous-time convergence

$$\begin{aligned}
 p_t \text{ gradient flow} \implies \partial_t \mathcal{F}(p_t) &= -\|\nabla \mathcal{F}(p_t)\|_{p_t}^2 \\
 \partial_t \mathcal{F}(p_t) \leq -2\alpha \mathcal{F}(p_t) &\stackrel{\text{Gronwall}}{\implies} \mathcal{F}(p_t) \leq \exp(-2\alpha t) \mathcal{F}(p_0)
 \end{aligned}$$

If  $\alpha = 0$ ,

$$\text{Lyapunov functional: } \mathcal{L}_t := t \mathcal{F}(p_t) + \frac{1}{2} d^2(p_t, p^*)$$

$$\partial_t \mathcal{L}_t = \mathcal{F}(p_t) - t \|\nabla \mathcal{F}(p_t)\|_{p_t}^2 + \langle \log_{p_t}(p^*), \nabla \mathcal{F}(p_t) \rangle_{p_t} \leq 0$$

$$\mathcal{L}_t \leq \mathcal{L}_0 \implies \mathcal{F}(p_t) \leq \frac{d^2(p_0, p^*)}{2t}$$

# Complements on Bures-SGD

We have  $g_p := \nabla_{BW}\mathcal{F}(p) = (\mathbb{E}_p[\nabla V], \mathbb{E}_p[\nabla^2 V] - \Sigma^{-1})$ , and therefore the stochastic gradient  $\hat{g}_p := (\nabla V(\hat{X}), \nabla^2 V(\hat{X}) - \Sigma^{-1})$ .

**Clip operator:**

$$\text{clip}^\tau : \Sigma = \sum_{i=1}^d \lambda_i u_i u_i^t \mapsto \text{clip}^\tau \Sigma := \sum_{i=1}^d (\lambda_i \wedge \tau) u_i u_i^t$$

**Lemma (Altschuler et al., 2023):** For any  $m \in \mathbb{R}^d$ ,  $\tau > 0$ , and  $\Sigma, \Sigma' \in \mathbb{S}_{++}^d$ ,

$$W_2(p_{m, \text{clip}^\tau \Sigma}, p_{m, \text{clip}^\tau \Sigma'}) \leq W_2(p_{m, \Sigma}, p_{m, \Sigma'})$$

# Proof of non-asymptotic guarantees

**Lemma:** If  $0 \prec \alpha I \preceq \nabla^2 V \preceq I$  and  $h \leq \alpha^2/60$ . Then, if in Bures-SGD,  $\Sigma_k \succeq \frac{\alpha}{9}I$ , then  $\Sigma_k^+ \succeq \frac{\alpha}{9}I$ .

**Sketch of proof:** The idea is to write  $\Sigma_k^+$  as a generalized Bures-Wasserstein barycenter at  $\Sigma_k$  for a certain distribution  $P$ , i.e.

$$\Sigma_k^+ = \exp_{\Sigma_k} \left( \int \log_{\Sigma_k}(\Sigma) dP(\Sigma) \right)$$

Then, some inequality results from Altschuler et al., 2023 are exploited.

# Proof of non-asymptotic guarantees

$$\mathcal{F}_k := \sigma(\hat{X}_0, \hat{X}_1, \hat{X}_2, \dots, \hat{X}_{k-1})$$

We bound

$$\mathbb{E}[W_2^2(p_{k+1}, \hat{\pi}) \mid \mathcal{F}_k] \leq \mathbb{E}[W_2^2(p_k^+, \hat{\pi}) \mid \mathcal{F}_k]$$

By writing the Wasserstein distance as expectation under the optimal coupling of  $X_k \sim p_k$  and  $Z \sim \hat{\pi}$  and then bounding it through strong convexity of  $\text{KL}(\cdot \parallel \pi)$ , it holds

$$\mathbb{E}[W_2^2(p_{k+1}, \hat{\pi}) \mid \mathcal{F}_k] \leq (1 - 2\alpha h) W_2^2(p_k, \hat{\pi}) + h^2 \text{err}$$

# Proof of non-asymptotic guarantees

Using the previous lemma, the definition of the stochastic gradient and Poincaré inequality, it holds

$$\text{err} \leq \frac{36d}{\alpha} + 6W_2^2(p_k, \hat{\pi})$$

Assuming  $h \leq \frac{\alpha^2}{60}$ ,

$$\mathbb{E}[W_2^2(p_{k+1}, \hat{\pi}) \mid \mathcal{F}_k] \leq (1 - \alpha h)W_2^2(p_k, \hat{\pi}) + \frac{36dh^2}{\alpha}$$

The theorem follows by iterating this result and by small step approximation.

# Complements on mixtures of Gaussians

Given  $(\mathcal{M}, g)$  Riemannian manifold,

$$\mathcal{P}_2(\mathcal{M}) := \{\mu \in \mathcal{P}(\mathcal{M}) \mid \int d^2(p_0, \cdot) d\mu < \infty \text{ for some } p_0 \in \mathcal{M}\}$$

$$W_2^2(\mu, \nu) := [\inf_{\gamma \in \mathcal{C}(\mu, \nu)} \int d^2(x, y) d\gamma(x, y)]$$

$$T_\mu \mathcal{P}_2(\mathcal{M}) := \overline{\{\nabla \psi \mid \psi \in \mathcal{C}_c^\infty(\mathcal{M})\}}^{L^2(\mu)}$$

$$\langle v, w \rangle_\mu := \int g_p(v(p), w(p)) d\mu(p)$$

Given a functional  $\mathcal{F}$ ,  $\nabla_{W_2} \mathcal{F}(\mu)$  is the element of  $T_\mu \mathcal{P}_2(\mathcal{M})$  such that, for any curve  $(\mu_t)_{t \geq 0}$  which satisfies the transport equation  $\partial_t \mu_t + \text{div}(\mu_t v_t) = 0$  with  $\mu_0 = \mu$ , it holds

$$\partial_t|_{t=0} \mathcal{F}(\mu_t) = \langle \nabla_{W_2} \mathcal{F}(\mu), v_0 \rangle_\mu = \int g(\nabla_{W_2} \mathcal{F}(\mu), v_0) d\mu$$

## Complements on mixtures of Gaussians

It follows, using the transport equation and integrating by parts, that

$$\nabla_{W_2} \mathcal{F}(\mu) = \nabla \delta \mathcal{F}(\mu)$$

where  $\delta \mathcal{F}(\mu) : \mathcal{M} \rightarrow \mathbb{R}$  is the first variation of  $\mathcal{F}$  at  $\mu$ . It satisfies

$$\partial_t|_{t=0} \mathcal{F}(\mu_t) = \int \delta \mathcal{F}(\mu) \partial_t|_{t=0} \mu_t$$

To find the system of ODEs for the KL divergence functional when  $\mathcal{M} = \text{BW}(\mathbb{R}^d)$ , the first variation of the functional is computed and its Bures-Wasserstein gradient. The ODEs for the evolution of the gradient flow then follow the relation

$$\dot{m}_0 = a$$

$$\dot{\Sigma}_0 = S\Sigma_0 + \Sigma_0 S$$

for every curve  $(m_t, \Sigma_t)_{t \geq 0}$  in the  $\text{BW}(\mathbb{R}^d)$  space with tangent vector  $(a, S)$  in 0.

# Lack of convexity

The functional  $\mu \mapsto \text{KL}(p_\mu \parallel \pi)$  is not convex even when  $\pi$  is strongly log-concave.

Let  $d = 1, V = 0$ , then  $\text{KL}(p_\mu \parallel \pi) = \mathcal{H}(p_\mu)$ . Let  $\mu_0 = \mathcal{N}(0, 1) \otimes \delta_1, \mu_1 = \mathcal{N}(0, \tau^2) \otimes \delta_1$ . For the optimal coupling,  $\sigma_0^2 = \sigma_1^2 = 1$  and  $m_1 = \tau m_0$ . The geodesic is thus  $\{\mu_t = \mathcal{N}(0, (1 - t + t\tau)^2) \otimes \delta_1\}_{t \in [0,1]}$ . Thus,

$$p_{\mu_t} = \int \mathcal{N}(m, \sigma^2) d\mu_t(m, \sigma^2) = \mathcal{N}(0, 1 + (1 - t + t\tau)^2)$$

Hence,

$$\mathcal{H}(p_{\mu_t}) = \int p_{\mu_t} \log p_{\mu_t} = -\frac{1}{2} \log(2\pi e) - \frac{1}{2} \log(1 + (1 - t + t\tau)^2)$$

Concave in  $[0, 1]$  for  $\tau = 1/2$ .

# Complements on HK (WFR) geometry

## Fisher-Rao (Hellinger)

- Space  $\mathcal{M}_+(\mathbb{R}^d)$  of positive measures.
- Fisher-Rao (Hellinger) distance:

$$d_{FR}^2(\mu_0, \mu_1) = \int (\sqrt{\mu_0} - \sqrt{\mu_1})^2$$

- Curves follow:

$$\partial_t \mu_t = \alpha_t \mu_t$$

$$\|\alpha\|_\mu^2 = \frac{1}{4} \int \alpha^2 d\mu$$

## Wasserstein

- Space  $\mathcal{P}_2(\mathbb{R}^d)$  of probability measures.
- Wasserstein distance.
- Curves follow:

$$\partial_t \mu_t + \operatorname{div}(\mu_t v_t) = 0$$

$$\|v\|_\mu^2 = \int \|v\|^2 d\mu$$

# Complements on HK (WFR) geometry

## Wasserstein-Fisher-Rao (Hellinger-Kantorovich) geometry

- Space  $\mathcal{M}_+(\mathbb{R}^d)$
- $T_\mu \mathcal{M}_+(\mathbb{R}^d) = \{(\alpha, \nu) \mid \exists u : \mathbb{R}^d \rightarrow \mathbb{R}, \alpha = u, \nu = \nabla u\}$
- Curves follow:

$$\partial_t \mu_t + \operatorname{div}(\mu_t \nu_t) = \alpha_t \mu_t$$

- Norm:

$$\|(\alpha, \nu)\|_\mu^2 = \int (\alpha^2 + \|\nu\|^2) d\mu$$

- Wasserstein-Fisher-Rao distance:

$$WFR^2(\mu_0, \mu_1) := \inf \left\{ \int_0^1 \|(\alpha_t, \nu_t)\|_{\mu_t}^2 dt \mid \begin{array}{l} (\mu_t, \alpha_t, \nu_t) \text{ solves reaction-diffusion PDE} \end{array} \right\}$$

# Complements on HK (WFR) geometry

The idea to develop the particle system algorithm is to define *particles with mass*  $(x_t, r_t)$  where the trajectory  $t \mapsto x_t$  develops along a diffusion process and the mass along a reaction process, i.e.

$$\dot{x}_t = v_t(x_t)$$

$$\dot{r}_t = (\alpha_t - \int \alpha_t d\mu_t) r_t \quad (\text{normalized to evolve in } \mathcal{P}_2(\mathcal{M}))$$

To derive the gradient flow, we take  $v_t$  and  $\alpha_t$  as the WFR gradient of the KL functional.

# Empirical results

Target: Bayesian logistic regression.

- synthetic dataset:  $\mathcal{D} = \{(x_i, y_i) : i = 1, \dots, N\}$ ;
- binary label  $y_i \in \{0, 1\}$ , given by ( $z \in \mathbb{R}^d$ )

$$\pi(y_i | x_i, z) = \sigma(x_i^t z)^{y_i} (1 - \sigma(x_i^t z))^{1-y_i}$$

- target posterior with uninformative prior:

$$\pi(z | \mathcal{D}) = \frac{1}{Z} \prod_{i=1}^N \pi(y_i | x_i, z)$$

- Langevin dynamic associated to:

$$-\nabla V(z) = \nabla \log \pi(z | \mathcal{D}) = \sum_{i=1}^N (y_i - \sigma(x_i^t z)) x_i$$

- $x_i$  generated from two Gaussian distributions  $\mathcal{N}(m_{y_i}^*, \Sigma^*)$  with separation factor  $\|m_1^* - m_0^*\| =: s$ .

# Empirical results

The  $\text{KL}(\hat{\pi} \parallel \pi)$  is computed up to the normalizing constant, i.e.,  $\text{KL}(\hat{\pi} \parallel \pi) - \log Z$ . As comparison it is taken the Laplace approximation, i.e.  $\hat{\pi}^{\text{Laplace}} = \mathcal{N}(z_0, (\nabla^2 \log \frac{1}{\pi}(z_0))^{-1})$ , obtained from the Taylor approximation of  $\log \pi(z)$  around a proper mode (point where the gradient is 0)  $z_0$  find with the L-BFGS algorithm.

# Gaussian VI (through Särkkä's integration) - $d = 2$

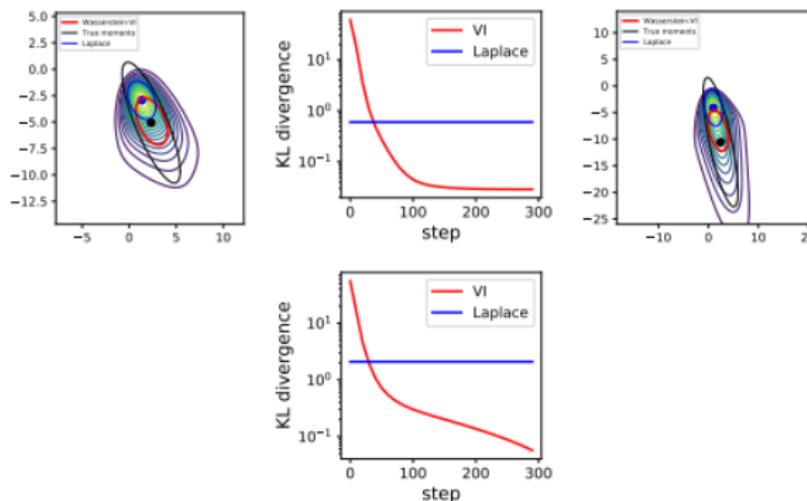


Figure 7: Results in dimension  $d = 2$ ,  $N = 10$  for a separation factor  $s = 1.5$  (upper row) and  $s = 2$  (lower row). The left column shows the true density via contour lines, the true mean (black dot) and covariance (black ellipsoid), and the results of the Laplace and Wasserstein VI approximations as blue and red ellipsoids respectively. The right column shows the evolution of the left KL divergence for Gaussian VI on a logarithmic scale. The corresponding KL divergence obtained with Laplace approximation is shown as a blue straight line.

# Gaussian VI (through Särkkä's integration) - $d = 10$

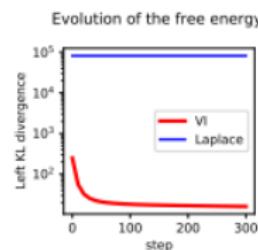
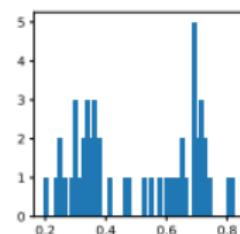
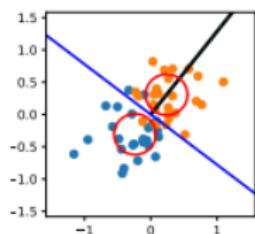
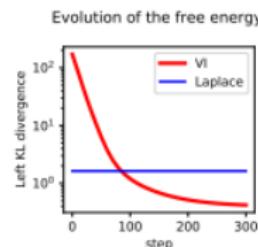
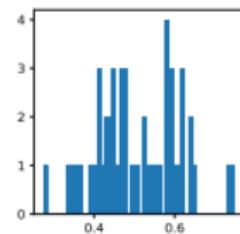
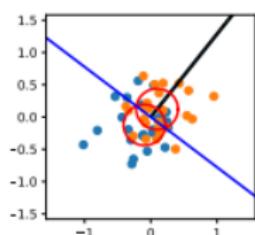


Figure 8: Results in dimension  $d = 10$ ,  $N = 50$  for a separation factor  $s = 0.6$  (upper row) and  $s = 1.5$  (lower row). Left column: synthetic dataset projected onto the two first coordinates. Middle column: histogram representing the number of examples predicted at a given probability by the obtained classifier. Right column: convergence in terms of unnormalized KL divergence. The unnormalized KL is computed via (55) letting  $Z = 1$  (upper row) and  $Z = 10^{20}$  (lower row). The Runge–Kutta step size is set to 0.1.

# Gaussian VI (through Särkkä's integration) - $d = 100$

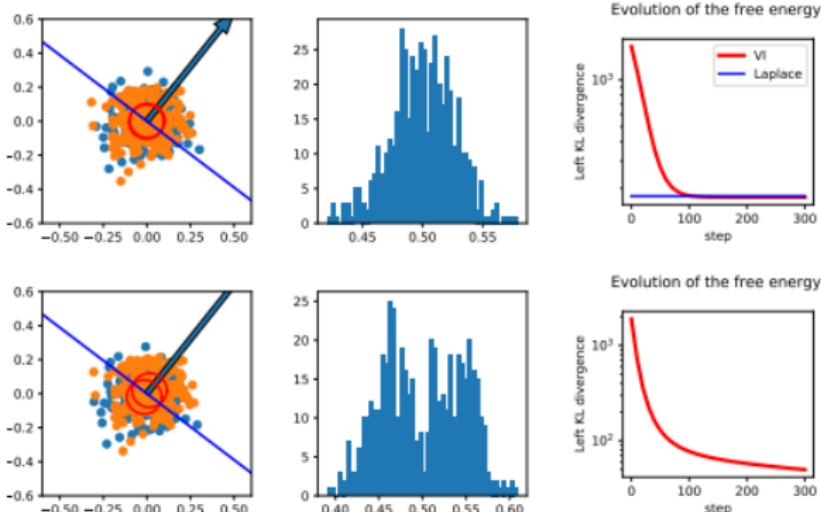


Figure 9: Same as Figure 8 but with dimension  $d = 100$ ,  $N = 500$ , with separation factor  $s = 0.05$  (upper row) and  $s = 0.3$  (lower row). The unnormalized KL is computed letting  $Z = 1$  (upper row) and  $Z = 10^{100}$  (lower row). The unnormalized KL divergence for the Laplace method is not shown in the lower plot because it is too large to be visualized.

# Mixture of Gaussian VI

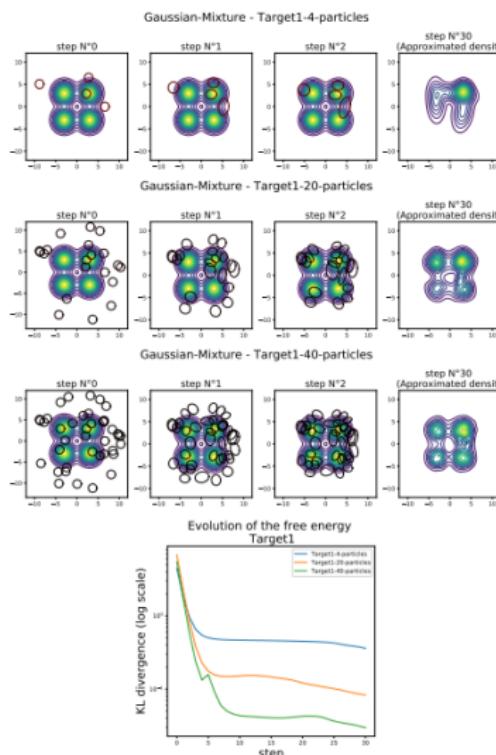


Figure 13: A target with 4 equally weighted modes and isotropic covariances.

# Mixture of Gaussian VI

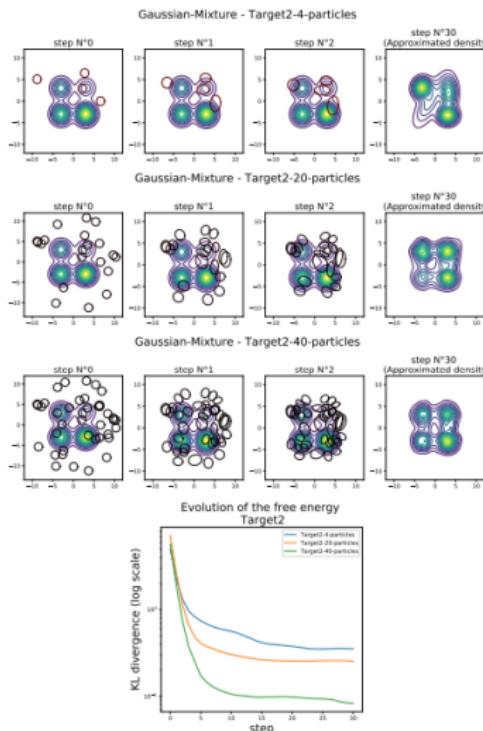
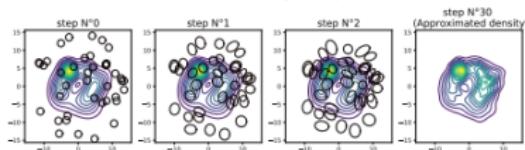
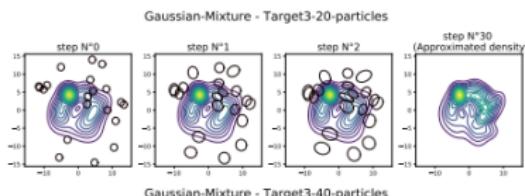
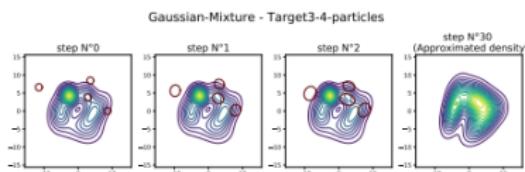
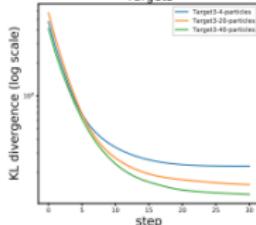


Figure 14: A target with 4 non-equally weighted modes and isotropic covariances.

# Mixture of Gaussian VI



Evolution of the free energy  
Target3



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